Nisan's Pseudorandom Generator for RL

$$\mathsf{BPL}\subseteq\mathsf{SC}=\mathsf{DTISP}(\mathsf{poly}(\mathit{n}),\mathsf{log}^2(\mathit{n}))$$

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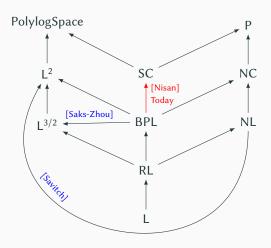
Complexity Classes

- L: Deterministic Logarithmic Space.
- L^{α} , $\alpha > 0$: Set of problems decidable in $O(\log^{\alpha} n)$ space deterministically.
- NL: Nondeterministic Logarithmic Space.
- RL: Randomized Logarithmic Space with One-sided error $\frac{1}{3}$.
- BPL: Randomized Logarithmic Space with Two-sided error $\frac{1}{3}$.
- SC: Steve's Class or DTISP(poly(n), poly(log n)) i.e. set of problems decidable deterministically in polynomial time and polylog space.
- NC: Nick's Class i.e. set of problems decidable in circuits of polynomial size and polylog depth and bounded fan-in.

Remark

Don't confuse SC with $P \cap PolylogSpace!$

Complexity Classes Zoo



Pseudorandom Generator

Definition (Pseudorandom Generator)

A map $G: \{0, 1\}^l \to \{0, 1\}^n$, where $n \ge l$ is called a PRG for a class C with a parameter $\epsilon > 0$ if for any $f \in C$,

$$\left| \underset{y \in \{0,1\}^n}{\mathbb{P}} [f(y) = 1] - \underset{x \in \{0,1\}^l}{\mathbb{P}} [f(\mathcal{G}(x)) = 1] \right| \le \epsilon$$

- Here *l* is called the seed-length of the PRG.
- n l is called the stretch of the PRG.
- We call G, ϵ -fools C.
- Typically, we want n >> l and G to be efficiently computable.

Finite State Automata

Let *T* be a BPL machine which uses n^c random bits on inputs of length *n* and runs in polynomial time and uses $S = O(\log n)$ space.

- There are at most $N := 2^{O(S)} = poly(n)$ configurations of T.
- Each random bit is used to make a transition between two configurations.
- The starting configuration is fixed for any input.
- Input x is accepted if T reaches a state representing acceptance.

Therefore the configuration graph of T on input x represents a finite state automata with N states.

Computational Tableau of BPL machine

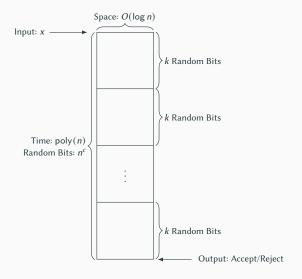


Figure 1: Computational Tableau of BPL machine *T*.

Dividing BPL Computation into Blocks

- Let the BPL machine T run in time T(n) = poly(n) using n^c random bits and $O(\log n)$ space on input x of length n.
- Let $k \ll n^c$ be a parameter to be fixed later.
- Divide the computation of *T* into $t = n^c/k$ blocks, where each block uses *k* random bits.
- We can treat each block as a separate BPL machine T_i (in some sense) which takes input as the final configuration of T_{i-1} and k random bits.

FSA for Computation Blocks

- We can think of *T* as a finite state automata with *N* states.
- Each state makes 2^k transitions where each transion corresponds to a choice of k random bits.
- Let Q be this automata. For transition we write Q(i; r) = j for any $r \in \{0, 1\}^k$ if Q goes from state i to state j when fed r.
- Let M be the matrix where $M[i,j] = \underset{r \in \{0,1\}^k}{\mathbb{P}} [Q(i;r) = j]$

$$\mathbb{P}_{r \in \{0,1\}^{k \times t}} [T(x,r) = \mathsf{Acc}] = \sum_{j: \mathsf{Accepting \, state}} M^t[1,j]$$

Goal: Approximate M^t using PRG.

Approximate Automata Matrix

Suppose we have a pseudorandom generator $\mathcal{G}: \{0,1\}^k \to \{0,1\}^{k \cdot t}$. Let Q be a finite state automata with N states and its matrix be M as defined above.

- From definition of M, $M^t[i,j] = \mathbb{P}_{r_1,\dots,r_t \in \{0,1\}^k}[Q(i;r_1\dots;r_t)=j]$
- Using \mathcal{G} , let $M_{\mathcal{G}}[i,j] = \underset{r \in \{0,1\}^k}{\mathbb{P}}[Q(i;\mathcal{G}(r)) = j]$
- Want to construct G such that

$$\|M^t - M_{\mathcal{G}}\| < \epsilon$$

for small ϵ .

Then if T decides a language with error probability at most $\frac{1}{3}$, using G we can calculate the $\sum_{j:\text{Accepting state}} M_G[1,j]$ and decide the language if it is at least $\frac{2}{3} - \epsilon$.

Matrix Norm

For any vector $v \in \mathbb{R}^N$, define $||v|| = \sum_{i \in [N]} |v(i)|$. Then for any matrix $M \in \mathbb{R}^{N \times N}$ define $||M|| = \sup_{0 \neq v \in \mathbb{R}^N} \frac{||Mv||}{||v||}$

Properties:

- $||M|| \le \max_{i \in [N]} \sum_{j \in [N]} |M[i, j]|$
- $||M + N|| \le ||M|| + ||N||$
- $||MN|| \le ||M|| \cdot ||N||$
- For our use-case M is row-stochastic, so ||M|| = 1

Universal Hash Family

Definition (Universal Hash Family (Carter-Wegman))

 $\mathcal{H} = \{h : \{0, 1\}^k \to \{0, 1\}^m\}$ is a universal hash family if for any $x_1 \neq x_2 \in \{0, 1\}^k$ and $y_1, y_2 \in \{0, 1\}^m$,

- $\mathbb{P}_{h \in \mathcal{H}}[h(x_1) = y_1] = \frac{1}{2^m}$
- $\mathbb{P}_{h \in \mathcal{H}}[h(x_1) = y_1 \land h(x_2) = y_2] = \frac{1}{2^{2m}}$

- For our purpose, we have k = m.
- We can construct such a family with $|\mathcal{H}| = 2^{O(k)}$ where each $h \in \mathcal{H}$ can be represented using O(k) bits and evaluated in poly(k) time over $GF(2^k)$.

Property of Universal Hash Family

Definition ((ϵ , A, B)-good hash function)

Let $A \subseteq \{0, 1\}^k$, $B \subseteq \{0, 1\}^m$, $\epsilon > 0$, $h : \{0, 1\}^k \to \{0, 1\}^m$ is said to be (ϵ, A, B) -good if

$$\left| \mathbb{P}_{x \in \{0,1\}^k} [x \in A \land h(x) \in B] - \alpha \cdot \beta \right| \le \epsilon$$

where $\alpha = \frac{|A|}{2^k}$ and $\beta = \frac{|B|}{2^m}$.

Lemma (Proved in Appendix)

If \mathcal{H} is a universal hash family, then for any $A \subseteq \{0, 1\}^k$, $B \subseteq \{0, 1\}^m$, $\epsilon > 0$,

$$\mathbb{P}_{h\in\mathcal{H}}[h \text{ is not } (\epsilon, A, B)\text{-good}] \leq \frac{\alpha \cdot \beta}{2^k \epsilon^2}$$

Nisan's Generator

Let \mathcal{H} be an universal hash family from $\{0, 1\}^k$ to $\{0, 1\}^k$. For any integer $m \ge 0$ define the function $\mathcal{G}_m \colon \{0, 1\}^k \times \mathcal{H}^m \to \{0, 1\}^{k \cdot 2^m}$ recursively as follows:

•
$$\mathcal{G}_0(x) = x$$

•
$$\mathcal{G}_m(x, h_1, \ldots, h_m) = (\mathcal{G}_{m-1}(x, h_1, \ldots, h_{m-1}), \mathcal{G}_{m-1}(h_m(x), h_1, \ldots, h_{m-1}))$$

For example:

$$G_1(x, h) = (x, h(x)), \quad G_2(x, h_1, h_2) = (x, h_1(x), h_2(x), h_1 \circ h_2(x))$$

$$\mathcal{G}_3(x, h_1, h_2, h_3) = (x, h_1(x), h_2(x), h_1 \circ h_2(x),$$
$$h_3(x), h_1 \circ h_3(x), h_2 \circ h_3(x), h_1 \circ h_2 \circ h_3(x))$$

- We want $k \cdot 2^m = n^c \implies m = \log t$.
- This gives a stretch of $k \cdot (t-1)$ bits.

Proof Flow

Let h_1, \ldots, h_s be some fixed hash functions from \mathcal{H} . Define the matrix

$$M_{h_1,...,h_s}[i,j] = \underset{x \in \{0,1\}^k}{\mathbb{P}} [Q(i;\mathcal{G}_s(x,h_1,...,h_s)) = j]$$

• Using h_1, \ldots, h_s we had 2^s many transitions in Q. So we should compare M_{h_1, \ldots, h_s} with M^{2^s} .

Goal: For 'good' choice of $h_1, \ldots, h_m, \|M^{2^m} - M_{h_1, \ldots, h_m}\| < \epsilon$

Approach:

Step 1: Suppose we have h_1, \ldots, h_{s-1} . We will find $h_s \in \mathcal{H}$ such that for all $i, j \in [N]$,

$$\left\|M_{h_1,\ldots,h_{s-1}}^2-M_{h_1,\ldots,h_s}\right\|\leq \delta$$

Step 2: Using above property will show for all $s \in [m]$,

$$\|M_{h_1,...,h_s} - M^{2^s}\| \le (2^s - 1)\delta$$

Find good h_s from h_1, \ldots, h_{s-1}

Suppose we have $h_1, \ldots, h_{s-1} \in \mathcal{H}$ such that,

$$\|M_{h_1,...,h_{l_{s-1}}} - M^{2^{s-1}}\| \le (2^{s-1} - 1)\delta$$

If we can find h_s such that $||M_{h_1,\dots,h_{s-1}}^2 - M_{h_1,\dots,h_s}|| \le \delta$ then we are done.

Algorithm (FIND): Go over all $h \in \mathcal{H}$ and all $i, j \in [N]$:

Step 1: Compute

- $p_1 = M_{h_1,...,h_{s-1},h}[i,j]$
- $p_2 = \sum_{l \in [N]} M_{h_1, \dots, h_{s-1}}[i, l] \cdot M_{h_1, \dots, h_{s-1}}[l, j]$

Step 2: Check if $|p_1 - p_2| > \frac{\delta}{N}$ go to next h else return h.

Remark

To compute $M_{h_1,\ldots,h_{s-1},h}[i,j]$ it goes over all $r \in \{0,1\}^k$ and compute $\mathcal{G}_s(r;h)1,\ldots,h_s)$ and counts how many r gives $Q(i;\mathcal{G}_s(r,h_1,\ldots,h_s))=j$ by simulating T. and return $count/2^k$.

Claim

There exists an $h_s \in \mathcal{H}$ such that for all $i, j \in [N]$,

$$\left| M_{h_1,...,h_{s-1},h_s}[i,j] - M_{h_1,...,h_{s-1}}^2[i,j] \right| \le \frac{\delta}{N}$$

Let $A_{i,j}$ be the set of $r \in \{0, 1\}^k$ such that $Q(i; \mathcal{G}_{s-1}(r, h_1, ..., h_{s-1})) = j$. So $M_{h_1,...,h_{s-1}}[i,j] = \rho(A_{i,j})$ where $\rho(A) = |A|/2^k$.

• For any $i, j \in [N]$,

$$M_{h_1,...,h_{s-1}}^2[i,j] = \sum_{l \in [N]} \rho(A_{i,l}) \cdot \rho(A_{l,j})$$

• For any $h \in \mathcal{H}$,

$$M_{h_1,...,h_{s-1},h}[i,j] = \sum_{l \in [N]} \mathbb{P}_{r \in \{0,1\}^k}[r \in A_{i,l} \land h(r) \in A_{l,j}]$$

For a random $h \in \mathcal{H}$ with probability at least $1 - \frac{N^4}{2^k \delta^2} \ge 1 - \frac{1}{2n^3}$,

$$\left| \mathbb{P}_{r \in \{0,1\}^k} [r \in A_{i,l} \wedge h(r) \in A_{l,j}] - \rho(A_{i,l}) \cdot \rho(A_{l,j}) \right| \leq \frac{\delta}{N^2}$$

So by Union Bound random $h \in \mathcal{H}$, $(\frac{\delta}{N^2}, A, B)$ -good for all A, B with probability at least $\frac{1}{2}$.

$$\begin{split} & \left| M_{h_1,\dots,h_{s-1}}^2 [i,j] - M_{h_1,\dots,h_{s-1},h} [i,j] \right| \\ & \leq \sum_{l \in [N]} \left| \underset{r \in \{0,1\}^k}{\mathbb{P}} [r \in A_{i,l} \wedge h(r) \in A_{l,j}] - \rho(A_{i,l}) \cdot \rho(A_{l,j}) \right| \\ & \leq N \cdot \frac{\delta}{N^2} = \frac{\delta}{N} \end{split}$$

Algorithm returns $good h_s$

Claim

If h_s is returned by the above algorithm, then

$$||M_{h_1,...,h_s} - M^{2^s}|| \le (2^s - 1)\delta$$

We have
$$\|M_{h_1,...,h_{s-1}}^2 - M_{h_1,...,h_s}\| \le \delta$$
.

$$\|M_{h_1,\dots,h_s}-M^{2^s}\|\leq \|M_{h_1,\dots,h_s}-M_{h_1,\dots,h_{s-1}}^2\|+\|M_{h_1,\dots,h_{s-1}}^2-M^{2^s}\|$$

$$\begin{split} \|M_{h_1,\dots,h_{s-1}}^2 - M^{2^s}\| &\leq \|M_{h_1,\dots,h_{s-1}}\| \cdot \|M_{h_1,\dots,h_{s-1}} - M^{2^{s-1}}\| \\ &+ \|M_{h_1,\dots,h_{s-1}} - M^{2^{s-1}}\| \cdot \|M^{2^{s-1}}\| \\ &\leq 1 \cdot (2^{s-1} - 1)\delta + (2^{s-1} - 1)\delta \cdot 1 = (2^s - 2)\delta \end{split}$$

Setting Parameters

• Set
$$k = \log(N) = O(\log n)$$
. So $t \approx n^c$.

• Set
$$m = \log t = O(\log n)$$
.

• Want
$$(2^m - 1)\delta = \epsilon \implies \delta = \frac{\epsilon}{2^m}$$

Final Algorithm

- Compute h_1, \ldots, h_m one by one using the algorithm FIND.
- Compute $A[i,j] = M_{h_1,...,h_m}[i,j]$ for all $i,j \in [N]$.
- Compute $\sum_{j:\text{Accepting state}} A[1,j]$ and accept if this is at least $\frac{2}{3} \epsilon$ else reject.

Space: The only place where more than $O(\log n)$ space is needed is to store the value of h_1, \ldots, h_m . And each h_i can be stored in $O(k) = O(\log n)$ space. So total space used is $O(\log^2 n)$.

Time: For all $s \in [m]$, computing $M_{h_1,\dots,h_s}[i,j]$ takes $O(2^k)$ times computation of $\mathcal{G}_s(r,h_1,\dots,h_s)$ for all r and to check if $Q(i;\mathcal{G}_s(r,h_1,\dots,h_s))=j$ which takes $O(2^m\cdot mk)\cdot T(n)$ time. So FIND takes $O(N^2\cdot 2^{2m}\cdot 2^{m+k}\cdot mk)\cdot T(n)$. Hence total time $O(N^2\cdot 2^{2m}\cdot 2^{m+k}\cdot mk)\cdot m\cdot T(n)=\operatorname{poly}(n)$.



Appendix i

Lemma

If \mathcal{H} is a universal hash family, then for any $A \subseteq \{0,1\}^k$, $B \subseteq \{0,1\}^m$, $\epsilon > 0$,

$$\mathbb{P}_{h\in\mathcal{H}}[h \text{ is not } (\epsilon, A, B)\text{-good}] \leq \frac{\alpha\beta(1-\beta)}{2^k\epsilon^2}$$

Consider the matrix $M \in \{0, 1\}^{2^k \times |\mathcal{H}|}$ where M[x, h] = 1 if $h(x) \in B$ and 0 otherwise. For any $x_1 \neq x_2 \in \{0, 1\}^k$, $\mathbb{E}_{h \in \mathcal{H}}[M[x_1, h]] = \beta$ and

$$\mathbb{E}_{h \in \mathcal{H}}[M[x_1, h]M[x_2, h]] = \beta^2$$

Appendix ii

$$\mathbb{E}_{h \in \mathcal{H}} \left[\left(\beta - \mathbb{E}_{x \in A} [M[x, h]] \right)^{2} \right] = \mathbb{E}_{x_{1}, x_{2} \in A} \mathbb{E}_{h \in \mathcal{H}} \left[(\beta - M[x_{1}, h]) (\beta - M[x_{2}, h]) \right]$$

$$= \mathbb{E}_{x_{1}, x_{2} \in A} \left[\beta^{2} - \beta \mathbb{E}_{h \in \mathcal{H}} [M[x_{1}, h]] - \beta \mathbb{E}_{h \in \mathcal{H}} [M[x_{1}, h]] + \mathbb{E}_{h \in \mathcal{H}} [M[x_{1}, h] \cdot M[x_{2}, h]] \right]$$

$$= \mathbb{E}_{x_{1}, x_{2} \in A} \left[\mathbb{E}_{h \in \mathcal{H}} [M[x_{1}, h] \cdot M[x_{2}, h]] - \beta^{2} \right]$$

- For $x_1 \neq x_2 : \underset{h \in \mathcal{H}}{\mathbb{E}} [M[x_1, h] \cdot M[x_2, h]] = \beta^2$
- For $x_1 = x_2 : \underset{h \in \mathcal{H}}{\mathbb{E}} [M[x_1, h] \cdot M[x_2, h]] = \underset{h \in \mathcal{H}}{\mathbb{E}} [M[x_1, h]] = \beta.$

Appendix iii

So,

$$\underset{h \in \mathcal{H}}{\mathbb{E}} \left[\left(\beta - \underset{x \in A}{\mathbb{E}} [M[x,h]] \right)^2 \right] = \frac{1}{|A|} (\beta - \beta^2) = \frac{\alpha \beta (1-\beta)}{2^k}$$

Now $\mathbb{P}_{x \in \{0,1\}^k}[x \in A \land h(x) \in B] = \alpha \mathbb{P}_{x \in A}[h(x) \in B] = \alpha \cdot \mathbb{E}_{x \in A}[M[x,h]]$. So h is not (ϵ, A, B) -good iff

$$\left| \underset{x \in A}{\mathbb{E}} [M[x, h]] - \beta \right| \ge \frac{\epsilon}{\alpha}$$

By Markov,

$$\mathbb{P}_{h \in \mathcal{H}}\left[\left|\beta - \mathbb{E}_{x \in A}[M[x, h]]\right| \ge \frac{\epsilon}{\alpha}\right] \le \frac{\alpha\beta(1 - \beta)}{2^k \epsilon^2}$$